

Vxworks Device Driver Development Explain

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- Device tree: CONFIG_OF_CONTROL If this variable is defined, U-Boot will use a device tree to configure its devices, instead of relying on statically compiled #defines in the board file. This option is experimental and only available on a few boards. The device tree is available in the global data as gd->fdt_blob.

GitHub - u-boot/u-boot: "Das U-Boot" Source Tree

A real-time operating system (RTOS) is an operating system (OS) intended to serve real-time applications that process data as it comes in, typically without buffer delays. Processing time requirements (including any OS delay) are measured in tenths of seconds or shorter increments of time. A real-time system is a time-bound system which has well-defined, fixed time constraints.

Real-time operating system - Wikipedia

VxWorks Options-mirtp -non-static -Bstatic -Bdynamic -Xbind-lazy -Xbind-now. ... Also print the version number of the compiler driver program and of the preprocessor and the compiler proper. -### ... This information is generally only useful to the G++ development team.

g++(1): GNU project C/C++ compiler - Linux man page

O Kernel Linux (Linux kernel em inglês) é um núcleo monolítico de código aberto para sistemas operacionais tipo UNIX.Desenvolvidas para ambos os sistemas computacionais, seja computadores pessoais ou servidores, normalmente na forma de distribuições Linux, e embarcados em diversos dispositivos como roteadores, pontos de acesso sem fio, PABXs, receptores de televisão, Smart TVs, DVRs, e ...

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